# SOME REMARKS ON THE LINEARIZATION OF THE EQUATIONS OF PLASTICITY 

## (NEKOTORYE ZAMECHANIIA O LINEARIZATSII URAVNENII PLASTICHNOSTI)

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Some remarks are herein made concerning the question of the linearization of the equations of plastic flow as applied to the simple problem of the drawing of a thin tube through a frictionless conical die (Fig. 1).


Fig. 1.


Fig. 2.

We define the stress- and strain-rate fields in the conical tube by the stress components $\sigma_{1}, \sigma_{2}$ the rate-of-strain components $\epsilon_{1}, \epsilon_{2}$ and the radial velocity $v$, remembering that

$$
\varepsilon_{1}=\frac{d v}{d r}, \quad \varepsilon_{2}=\frac{v}{r}
$$

The differential equation of equilibrium of the conical tube of thickness $h$ has the form

$$
\begin{equation*}
\frac{d\left(h \sigma_{1}\right)}{d r}+\frac{h\left(\sigma_{1}-\sigma_{2}\right)}{r}=0 \tag{1}
\end{equation*}
$$

while the plasticity condition is

$$
\begin{equation*}
\Phi\left(\sigma_{1}, \sigma_{2}\right)=\sigma_{s} \tag{2}
\end{equation*}
$$

The relations between the stress components and the rate-of-strain
components are

$$
\frac{\varepsilon_{1}}{\partial \Phi / \partial \sigma_{1}}=\frac{\varepsilon_{2}}{\partial \Phi / \partial \sigma_{2}} \quad \text { or } \quad \frac{\varepsilon_{1}}{2 J_{1}-\sigma_{2}}=\frac{\varepsilon_{2}}{2 \sigma_{2}-\sigma_{1}}
$$

which lead to

$$
\begin{equation*}
\frac{d v}{d r}+m \frac{v}{r}=0, \quad m=-\frac{\partial \Phi / \partial \sigma_{p}}{\partial D / \partial \sigma_{2}} \tag{3}
\end{equation*}
$$

The usual condition of incompressibility of the material requires that

$$
\begin{equation*}
\frac{d}{d r}(r v h)=0 \tag{4}
\end{equation*}
$$

We note that even small variations in the function $\Phi$ may cause large changes in $\partial \Phi / \partial \sigma_{1}$ and $\partial \Phi / \partial \sigma_{2}$, and hence in the coefficient m.

A solution of the above problem obtained by Swift [1] was based on the usual plasticity condition

$$
\sigma_{1}^{2}-\sigma_{1} \sigma_{2}+\sigma_{2}^{2}=\sigma_{\mathrm{s}}^{2}
$$

which may be represented by an ellipse in the $\sigma_{1}, \sigma_{2}$-plane. The stress components $\sigma_{1}, \sigma_{2}$ at the place where the tube enters the die and at the place where it leaves it are depicted by the points $A$ and $B$ (Fig. 2). From this it is clear that

$$
\Phi^{2}=\sigma_{1}^{2}-\sigma_{1} \sigma_{2}+\sigma_{2}^{2}, \quad m=\frac{2 \sigma_{1}-\sigma_{2}}{2_{2}-\sigma_{2}}
$$

The stress components $\sigma_{1}$ and $\sigma_{2}$ in this solution, as well as the radial velocity $v$ and the thickness $h$, may be represented in closed form, and

$$
r v h=a r_{0} h_{0}
$$

We note that for $b / a=0.425$, the principal stress $\sigma_{2}$ at the point where the tube leaves the die is equal to zero, while the ratio $h / h_{0}=$ 1.054 .

A graph of the function $h / h_{0}$, which determines the variation of the thickness of the conical tube along a generator, is shown in Fig. 3.

A solution of the same problem was presented by Prager [2] for a linearized plasticity condition

$$
\mu \sigma_{1}-\sigma_{2}=\sigma_{s}
$$

which can be represented by a straight line in the $\sigma_{1}, \sigma_{2}$-plane.
The stress components $\sigma_{1}, \sigma_{2}$ at the place where the tube enters the die and the place where it leaves it are denoted by the points $A$ and $B$,


Fig. 3.


Fig. 4.
as before. It is clear that

$$
\Phi=\mu \sigma_{1}-\sigma_{2}, \quad m=\mu
$$

The stress components $\sigma_{1}$ and $\sigma_{2}$ take the form

$$
\begin{equation*}
\sigma_{1}=\sigma_{s} \ln \frac{a}{r}, \quad \sigma_{2}^{-}=\sigma_{s}\left(\mu \ln \frac{a}{r}-1\right) \tag{5}
\end{equation*}
$$

and the radial velocity $v$ and thickness $h$ are

$$
\begin{equation*}
v=v_{0}\left(\frac{a}{r}\right)^{\mu}, \quad h=h_{0}\left(\frac{a}{r}\right)^{1-\mu} \tag{6}
\end{equation*}
$$

The parameter $\mu$ should be determined from the condition that the stress components $\sigma_{1}$ and $\sigma_{2}$ at $r=b$ satisfy the relation

$$
\sigma_{1}{ }^{2}-\sigma_{1} \sigma_{2}+\sigma_{2}^{2}=\sigma_{s}{ }^{2}
$$

or that the point $B$ lie on an arc of the ellipse.
This condition determines the relation

$$
\frac{b}{a}=\exp \left(\frac{1-2 \mu}{1-\mu+\mu^{2}}\right)
$$

which yields

$$
\begin{aligned}
b / a & =0.4 \\
\mu & =0.927
\end{aligned}
$$

$$
0.5
$$

$$
\begin{aligned}
& 0.6 \\
& 0.702
\end{aligned}
$$

$$
0.7
$$

$$
0.8
$$

$$
0.9
$$

1.0

We remark that for a ratio $b / a=0.368$, i. e. for $\mu=1$, the stress component $\sigma_{2}$ at the point where the tube leaves the die is equal to zero, while the thickness of the tube is the same everywhere, i.e. $h=h_{0}$.

Curves of the function $h / h_{0}$, representing the variation in the thickness of the conical tube along a generator, are presented for various
values of $b / a$ from 0.4 to 1.0 in Fig. 4.
Comparison of the graphs of the functions $h / h_{0}$ in Figs. 3 and 4 shows that they have different forms, although the corresponding stress components $\sigma_{1}$ at the place where the tube leaves the die are in fairly close agreement.

## BIBLIOGRAPHY

1. Swift, H., Stresses and strains in tube drawing. Phil. Mag. No. 40, 1949.
2. Prager, W., An Introduction to Plasticity, Addison-Wesley, 1959.
